



# Observing through the Turbulent Atmosphere

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# Plan of this Talk

- A few useful results from Fourier theory
- Motivation of the Kolmogorov model for turbulence
- Statistical description of Kolmogorov turbulence
- Wave propagation through turbulence
- Image formation by telescopes and the effect of turbulence on images
- Useful parameters that describe turbulence

# Convolution, Correlation, and Structure Function



- Convolution:  $g * h \equiv \int_{-\infty}^{\infty} g(t - \tau) h(\tau) d\tau$
- Correlation:  $Corr(g, h) \equiv \int_{-\infty}^{\infty} g(t + \tau) h(\tau) d\tau$
- Covariance:  $B_g \equiv Corr(g, g)$
- Structure function:  $D_g(t_1, t_2) \equiv \langle |g(t_1) - g(t_2)|^2 \rangle$
- If  $g$  describes a homogeneous and isotropic process,  $D_g$  depends only on  $t \equiv |t_1 - t_2|$ , and
$$D_g(t) = 2[B_g(0) - B_g(t)]$$

# A few Important Results from Fourier Theory



- Convolution theorem

$$g * h \Leftrightarrow G(f) \cdot H(f)$$

- Correlation theorem

$$\text{Corr}(g, h) \Leftrightarrow G(f) \cdot H^*(f)$$

- Wiener-Khinchin theorem

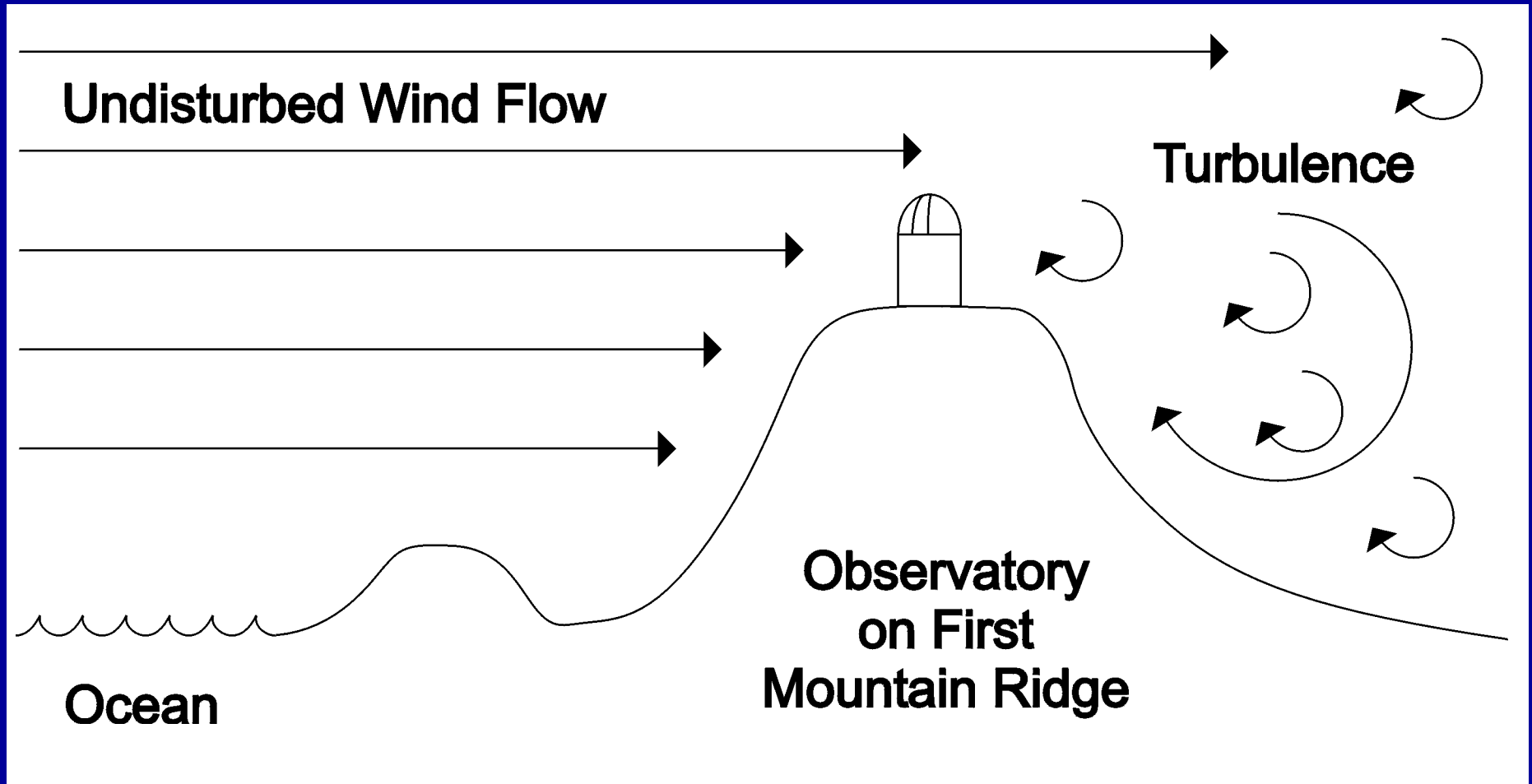
$$\text{Corr}(g, g) \Leftrightarrow |G(f)|^2$$

- Parseval's theorem

$$\text{Total Power} \equiv \int_{-\infty}^{\infty} |h(t)|^2 dt = \int_{-\infty}^{\infty} |H(f)|^2 df$$



# Turbulence Generation

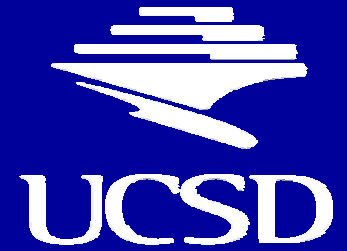


# The Kolmogorov Turbulence Model



- For atmospheric flows the Reynolds number  $Re \equiv VL / \nu \geq 10^6 \Rightarrow$  flow is highly turbulent
- Turbulent energy is generated on large scale  $L_0$ , dissipated on small scale  $l_0$
- $L_0$  is called *outer scale*,  $l_0$  is called *inner scale*
- In the *inertial range* between  $l_0$  and  $L_0$ , there is a universal description for the turbulence spectrum
- The only two relevant parameters are the rate of energy generation  $\varepsilon$  and the kinematic viscosity  $\nu$

# The Structure Function of Kolmogorov Turbulence



- The units of  $\nu$  are  $\text{m}^2\text{s}^{-1}$ , the dimensions of  $\varepsilon$  are  $\text{J s}^{-1}\text{kg}^{-1} = \text{m}^2\text{s}^{-3}$
- The velocity structure function can be written as
$$D_v(R_1, R_2) \equiv \left\langle |v(R_1) - v(R_2)|^2 \right\rangle$$
$$= \alpha \cdot f(|R_1 - R_2| / \beta)$$
- The dimensions of  $\alpha$  are  $\text{m}^2\text{s}^{-2} \Rightarrow \alpha = \nu^{1/2} \varepsilon^{1/2}$
- The dimensions of  $\beta$  are  $\text{m} \Rightarrow \beta = \nu^{3/4} \varepsilon^{-1/4}$

# Completion of Dimensional Analysis



- In the inertial range dissipation plays no role  
 $\Rightarrow$  dependence on  $\nu$  must drop out
- This is possible only if  $f = k \cdot (|R_1 - R_2| / \beta)^{2/3}$
- We can therefore write
$$D_\nu(R_1, R_2) = C_\nu^2 |R_1 - R_2|^{2/3}$$
- The constant  $C_\nu^2$  describes the strength of the turbulence



# Structure Function of the Refractive Index



- Turbulence carries “parcels” of air with different temperature
- The parcels are in pressure equilibrium and thus have different density and index of refraction
- The corresponding structure functions are

$$D_T(R_1, R_2) = C_T^2 |R_1 - R_2|^{2/3} \quad \text{and}$$

$$D_N(R_1, R_2) = C_N^2 |R_1 - R_2|^{2/3} \quad \text{with}$$

$$C_N = \left( 78 \cdot 10^{-6} p[\text{mbar}] / T^2 [\text{K}] \right) \cdot C_T$$

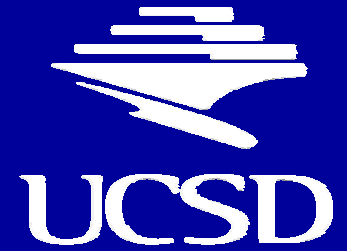
# The Power Spectrum of the Refractive Index



- The structure function  $D$  is related to the covariance  $B$  by  $D(R) = 2[B(0) - B(R)]$
- The covariance  $B$  is the Fourier transform of the power spectral density  $\Phi$  (Wiener-Khinchin theorem)
- We can thus compute  $\Phi$  from  $D$
- For Kolmogorov turbulence the result is

$$\Phi(\kappa) = 0.0365 C_N^2 \kappa^{-5/3}$$

# The Effect of a Turbulent Layer



- We look at the propagation of a wavefront  $\psi(x) = \exp[i\phi(x)]$  through a turbulent layer of thickness  $\delta h$  at height  $h$
- The phase shift produced by refractive index fluctuations is

$$\phi(x) = k \int_h^{h+\delta h} dz \, n(x, z)$$

# The Coherence Function of the Wavefront



- We will need the *coherence function* of the wavefront

$$\begin{aligned} B_h(r) &\equiv \langle \psi(x+r) \psi^*(x) \rangle \\ &= \langle \exp i[\phi(x) - \phi(x+r)] \rangle \\ &= \exp \left[ -\frac{1}{2} \langle |\phi(x) - \phi(x+r)|^2 \rangle \right] \\ &= \exp \left[ -\frac{1}{2} D_\phi(r) \right] \end{aligned}$$

- Next goal: calculate  $D_\phi(r)$

# Expectation Value of Exponential



- Let  $\chi$  be a Gaussian variable with zero mean and variance  $\sigma^2$

- $$\begin{aligned}\langle \exp(\alpha\chi) \rangle &\equiv \frac{1}{\sqrt{2\pi\sigma}} \int_{-\infty}^{\infty} d\chi \exp(\alpha\chi) \exp\left(-\frac{\chi^2}{2\sigma^2}\right) \\ &= \frac{1}{\sqrt{2\pi\sigma}} \int_{-\infty}^{\infty} d\chi \exp\left[-\frac{1}{2}\left(\frac{\chi^2}{\sigma^2} - 2\alpha\chi\right)\right] \\ &= \frac{1}{\sqrt{2\pi\sigma}} \int_{-\infty}^{\infty} d\chi \exp\left[-\frac{1}{2\sigma^2}(\chi - \alpha\sigma^2)^2\right] \cdot \exp\left(\frac{1}{2}\alpha^2\sigma^2\right) \\ &= \frac{1}{\sqrt{2\pi\sigma}} \int_{-\infty}^{\infty} d\tilde{\chi} \exp\left(-\frac{\tilde{\chi}^2}{2\sigma^2}\right) \cdot \exp\left(\frac{1}{2}\alpha^2\sigma^2\right) \\ &= \exp\left(\frac{1}{2}\alpha^2\langle\chi^2\rangle\right)\end{aligned}$$

# Phase Covariance

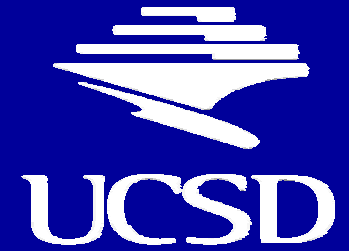
- With  $z \equiv z' - z''$

$$\begin{aligned} B_{\phi}(r) &\equiv \langle \phi(x) \phi(x+r) \rangle \\ &= k^2 \int_h^{h+\delta h} \int_h^{h+\delta h} dz' dz'' \langle n(x, z') n(x+r, z'') \rangle \\ &= k^2 \int_h^{h+\delta h} dz' \int_{h-z'}^{h+\delta h-z'} dz B_N(r, z) \end{aligned}$$

- For  $\delta h$  much larger than the correlation scale

$$B_{\phi}(r) = k^2 \delta h \int_{-\infty}^{\infty} dz B_N(r, z)$$

# Computation of the Phase Structure Function



- $$\begin{aligned} D_\phi(r) &= 2[B_\phi(0) - B_\phi(r)] \\ &= 2k^2 \delta h \int_{-\infty}^{\infty} dz [B_N(0, z) - B_N(r, z)] \\ &= 2k^2 \delta h \int_{-\infty}^{\infty} dz \\ &\quad [(B_N(0, 0) - B_N(r, z)) - (B_N(0, 0) - B_N(0, z))] \\ &= k^2 \delta h \int_{-\infty}^{\infty} dz [D_N(r, z) - D_N(0, z)] \\ &= k^2 \delta h C_N^2 \int_{-\infty}^{\infty} dz \left[ (r^2 + z^2)^{1/3} - z^{2/3} \right] \\ &= 2.914 k^2 \delta h C_N^2 r^{5/3} \end{aligned}$$

# The Wavefront Coherence Function



- For the layer under consideration we have obtained

$$B_h(r) = \exp\left[-\frac{1}{2}\left(2.914 k^2 C_N^2 \delta h r^{5/3}\right)\right]$$

- Integration over the whole atmosphere, and taking the zenith angle  $z$  into account gives

$$B(r) = \exp\left[-\frac{1}{2}\left(2.914 k^2 (\sec z) r^{5/3} \int dh C_N^2(h)\right)\right]$$



# The Fried Parameter $r_0$

- We define the *Fried parameter*  $r_0$  by

$$r_0 \equiv \left[ 0.423 k^2 (\sec z) \int dh C_N^2(h) \right]^{-3/5}$$

- Now we can write

$$B(r) = \exp \left[ -3.44 \left( \frac{r}{r_0} \right)^{5/3} \right] \quad \text{and}$$

$$D_\phi(r) = 6.88 \left( \frac{r}{r_0} \right)^{5/3}$$

# Fraunhofer Diffraction

- The complex amplitude  $A$  of a wave  $\psi$  diffracted at an aperture  $P$  with area  $\Pi$  can be computed from Huygens' principle

- In the far field  $A$  is thus given by

$$A(\alpha) = \frac{1}{\sqrt{\Pi}} \int dx \psi(x) P(x) \exp[-2\pi i \alpha x / \lambda]$$

- With  $u \equiv x / \lambda$  we can write

$$A(\alpha) = \frac{1}{\sqrt{\Pi}} FT[\psi(u) P(u)]$$

# Optical Image Formation

- The intensity distribution in the focal plane (point spread function) is

$$S(\alpha) = |A(\alpha)|^2 = \frac{1}{\Pi} \left| FT[\psi(u)P(u)] \right|^2$$

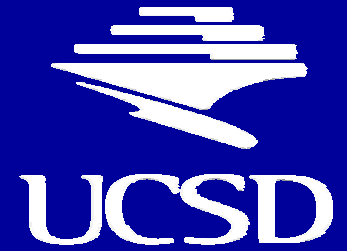
- From the Wiener-Khinchin theorem we get

$$\begin{aligned} \langle S(f) \rangle &= \frac{1}{\Pi} \int du \langle \psi(u) \psi^*(u+f) \rangle P(u) P^*(u+f) \\ &= B(f) T(f) \end{aligned}$$

- Here we have introduced the *telescope transfer function*

$$T(f) = \frac{1}{\Pi} \int du P(u) P^*(u+f)$$

# Resolving Power and Diffraction-Limited Images



- We define the *resolving power*  $R$  by

$$R \equiv \int df B(f) T(f)$$

- In the absence of turbulence,  $B = 1$ , and

$$R = R_{\text{tel}} = \int df T(f)$$

$$= \frac{1}{\Pi} \iint du df P(u) P^*(u + f)$$

$$= \frac{1}{\Pi} \left| \int du P(u) \right|^2 = \frac{\pi}{4} \left( \frac{D}{\lambda} \right)^2$$

- The last equality holds for a circular aperture

# Seeing-Limited Images

- For strong turbulence  $T = 1$  in the region where  $B$  is non-zero, and

$$\begin{aligned} R &= R_{\text{atm}} = \int df B(f) \\ &= \int df \exp[-Kf^{5/3}] \\ &= \frac{6\pi}{5} \Gamma\left(\frac{6}{5}\right) K^{-6/5} = \frac{6\pi}{5} \Gamma\left(\frac{6}{5}\right) \cdot \left[3.44 \left(\frac{\lambda}{r_0}\right)^{5/3}\right]^{-6/5} \\ &= \frac{\pi}{4} \left(\frac{r_0}{\lambda}\right)^2 \end{aligned}$$

# Significance of the Fried Parameter $r_0$



- The resolution of long exposures through the atmosphere is the same as the resolution obtained with a telescope of diameter  $r_0$
- The phase variance over an aperture with diameter  $r_0$  is approximately  $1 \text{ rad}^2$
- $r_0$  depends on the turbulence profile  $C_N^2(h)$ , the zenith angle  $z$ , and the observing wavelength  $\lambda$
- The wavelength dependence is  $r_0 \propto \lambda^{6/5}$ ; this leads to an image size (“seeing”)  $\alpha \propto \lambda / r_0 \propto \lambda^{-1/5}$

# Typical Value of $r_0$

- At good sites and under good conditions,  $r_0$  at 500 nm is typically in the range 10...20 cm
- This corresponds to an image size of 0.5" ... 1"
- At any site, the night-to-night variations of  $r_0$  are large
- There are also short-term fluctuations on all time scales, which complicate the calibration of high-resolution observations

# The Strehl Ratio

- The quality of an imaging system is often measured by the *Strehl ratio*  $S$ , defined as the on-axis intensity in the actual image divided by the peak intensity in a diffraction-limited image
- For phase errors  $\leq 2$  rad,  $S \approx \exp\left[-\sigma_\phi^2\right]$
- The Hubble Space Telescope optics have  $S \approx 0.1$  (without corrective optics)
- A telescope with diameter  $r_0$  delivers  $S = 0.37$  (without tip-tilt correction)



# Practical Consequences of Non-Perfect Strehl Ratio



- If  $S \geq 0.1$ , image deconvolution software can usually be used to obtain diffraction-limited images, but the dynamic range is limited
- In an interferometer the visibility cannot be better than  $S$
- The coupling efficiency into single-mode fibers is approximately equal to  $S$
- For telescopes with size up to  $\sim 3r_0$  tip-tilt correction can dramatically improve  $S$

# Taylor's "Frozen Turbulence"

## Hypothesis and $\tau_0$



- It is frequently assumed that the time constant for changes in the turbulence pattern is much longer than the time it takes the wind to blow the turbulence past the telescope aperture
- Atmospheric turbulence is often dominated by a single layer
- The temporal behavior of the turbulence can therefore be characterized by a time constant  $\tau_0 \equiv r_0 / v$ , where  $v$  is the wind velocity in the dominant layer

# Short and Long Exposures

- Observations with exposure time  $t \ll \tau_0$  (so-called “short exposures”) produce images through one instantaneous realization of the atmosphere (“speckle images”)
- Long exposures with  $t \gg \tau_0$  average over the atmospheric random process
- In an interferometer  $\tau_0$  sets the time scale for detector readout or fringe tracking

# Phase Variance between Rays from two Stars



- The rays “from” the telescope “to” two stars separated by an angle  $\theta$  coincide at the pupil; at a distance  $d$  their separation is  $r = \theta d = \theta h \sec z$
- We insert this relation in
- The result is

$$\left\langle |\phi(0) - \phi(r)|^2 \right\rangle = D_\phi(r) = 2.914 k^2 \sec z \delta h C_N^2 r^{5/3}$$

$$\begin{aligned} \left\langle \sigma_\phi^2 \right\rangle &= 2.914 k^2 \sec z \int dh C_N^2(h) (\theta h \sec z)^{5/3} \\ &= 2.914 k^2 (\sec z)^{8/3} \theta^{5/3} \int dh C_N^2(h) h^{5/3} \end{aligned}$$

# Angular Anisoplanatism

- We define

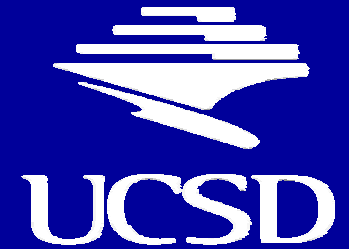
$$\theta_0 \equiv \left[ 2.914 k^2 (\sec z)^{8/3} \int dh C_N^2(h) h^{5/3} \right]^{-3/5}$$

- Now we can write

$$\left\langle \sigma_\phi^2 \right\rangle_{\text{aniso}} = \left( \frac{\theta}{\theta_0} \right)^{5/3}$$

- Anisoplanatism is dominated by high layers
- The short-exposure point spread functions for two stars separated by more than  $\theta_0$  are different, but the long-exposure psf's are (nearly) identical

# Fresnel Length and Diffraction Effects

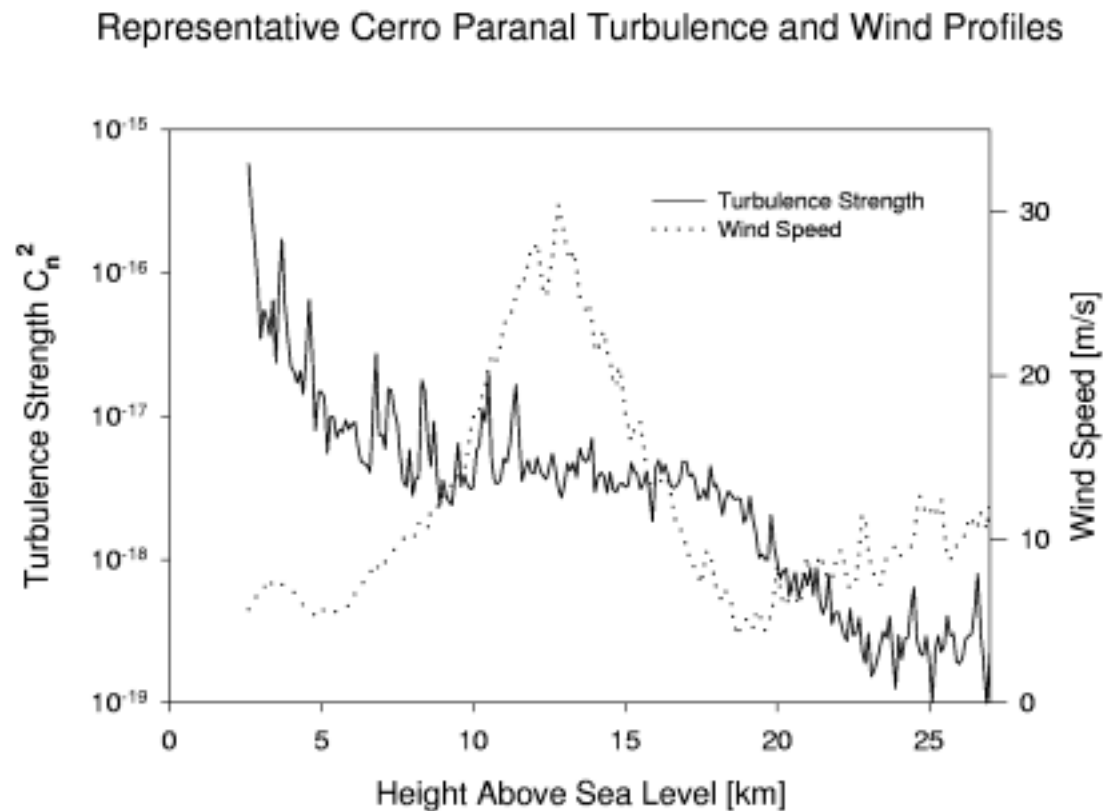


- The geometric optics approximation of propagation is only valid for paths shorter than the *Fresnel propagation length*  $d_F \equiv r_0^2 / \lambda$
- For  $r_0 = 10$  cm,  $\lambda = 500$  nm, the Fresnel length is 20 km
- The geometric approximation is therefore a good first-order approach, but diffraction is not negligible, especially at short wavelengths, large zenith angles, and poor observing sites

# Scintillation

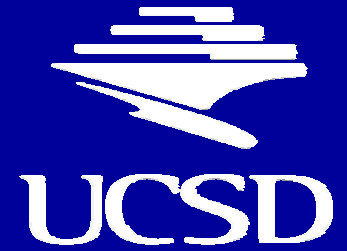
- Diffraction gives rise to *scintillation*, i.e., intensity fluctuations that are important for photometry if the exposure time is short
- The local intensity fluctuations are given by
$$\sigma_{\ln I}^2 = 2.24 k^{7/6} (\sec z)^{11/6} \int dh C_N^2(h) h^{5/6}$$
- Scintillation is dominated by high-altitude turbulence
- For telescopes larger than the Fresnel scale
$$r_F \equiv \sqrt{\lambda h \sec z}$$
, aperture averaging is important

# Turbulence Profiles





# Consequences for Optical / Infrared Interferometry



- Optical interferometers with telescopes larger than  $r_0$  need adaptive optics (tip-tilt correction only is sufficient up to  $3r_0$ )
- The search radius for dual-star interferometry is limited by anisoplanatism
- Null depth is limited by atmospheric residuals
- Fringe tracking servos or detector readouts must work on the atmospheric time scale

# Atmospheric Phase Noise and Fringe Tracking



- The power spectrum of atmospheric phase fluctuations (Kolmogorov approximation) is
$$\Phi_{\phi}(f) = 0.077 \tau_0^{-5/3} f^{-8/3}$$
- If  $H(f)$  is the closed-loop fringe servo transfer function, the residual phase variance is given by
$$\sigma_R^2 = \int_0^{\infty} df |1 - H(f)|^2 \Phi_{\phi}(f)$$
- Define the *Greenwood frequency* by
$$f_G \equiv \left[ 0.102 k^2 (\sec z) \int dh C_N^2(h) \nu^{5/3}(h) \right]^{3/5}$$

# Null Depth in the Presence of Phase Noise



- In many cases, the null depth due to residual phase fluctuations can be written as

$$\overline{N} = \frac{1}{4} \sigma_R^2 = \frac{1}{2} \kappa \left( \frac{f_G}{f_S} \right)^{5/3}$$

- $\kappa = 0.191$  for sharp cutoff,  $\kappa = 1$  for RC filter,  $\kappa = 28.4$  for pure delay (loop lag)
- Detailed modeling of fringe tracking servo needed

# Numerical Estimate of Fringe Tracking Residuals



- Assume a servo with a 2 ms “pure delay”
- Assume  $f_G = 21.35$  Hz at  $\lambda = 500$  nm  
(corresponds to  $r_0 = 20$  cm,  $v = 10$  m/s)
- For these parameters the null depth is  $6.3 \cdot 10^{-3}$  at K band
- The null depth due to high-frequency fringe tracking residuals scales with  $\lambda^{-5/3}$

# Literature References

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